
Reliable Uncertainty Quantification

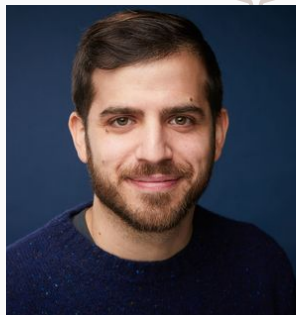
Advances in Calibration and
Likelihood-Free Inference

Rafael Izbicki (UFSCar)

Agradecimentos: FAPESP, CAPES, CNPq



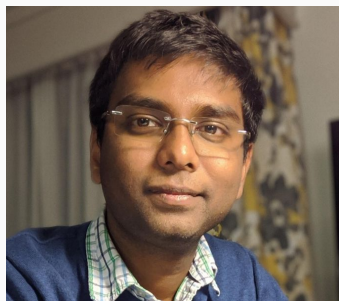
L. Masserano
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Jeffrey A. Newman
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Brett H. Andrews
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T. Dorigo (INFN)

Towards Instance-Wise Calibration: Local Amortized Diagnostics and Reshaping of Conditional Densities (LADaR)

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Monthly Notices

of the

ROYAL ASTRONOMICAL SOCIETY

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Evaluation of probabilistic The Rubin Observatory L

S. J. Schmidt¹,¹★ A. I. Malz,^{2,3,4}★ J.
J. Cohen-Tanugi,¹¹ A. J. Connolly,¹²
K. G. Iyer,^{19,20} M. J. Jarvis¹²,^{21,22} J. I.
C. B. Morrison,¹² J. A. Newman,²⁴ E.
R. H. Wechsler,^{16,25,26} R. Zhou^{15,24}

Photo-z Code	CDE Loss
ANNz2	−6.88
BPZ	−7.82
Delight	−8.33
EAZY	−7.07
FlexZBoost	−10.60
GPz	−9.93
LePhare	−1.66
METAPhoR	−6.28
CMNN	−10.43
SkyNet	−7.89
TPZ	−9.55
trainZ	−0.83



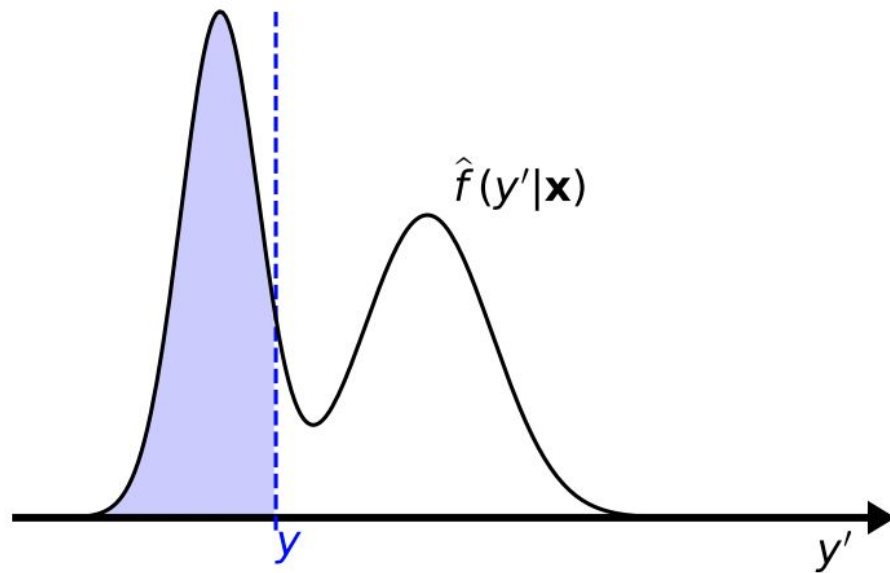
doi:10.1093/mnras/staa2799

nation approaches for Time (LSST)

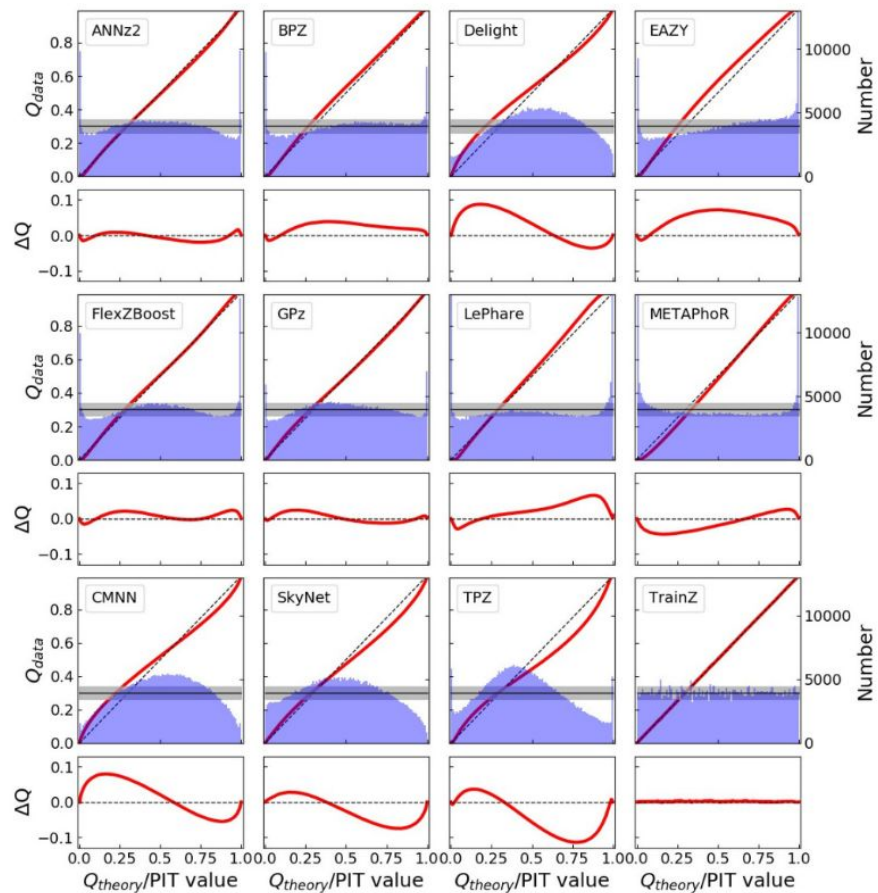
M. Brescia⁹,⁹ S. Caviuoti,^{9,10}
M. L. Graham¹²,¹²
G. Longo,¹⁰
H. Tranin,¹¹
(Energy Science Collaboration)



Probability Integral Transform (PIT)



$$\text{PIT}(Y_1; \mathbf{X}_1), \dots, \text{PIT}(Y_n; \mathbf{X}_n) \stackrel{i.i.d.}{\sim} \text{Unif}(0, 1)$$



Algorithm 1 Cal-PIT

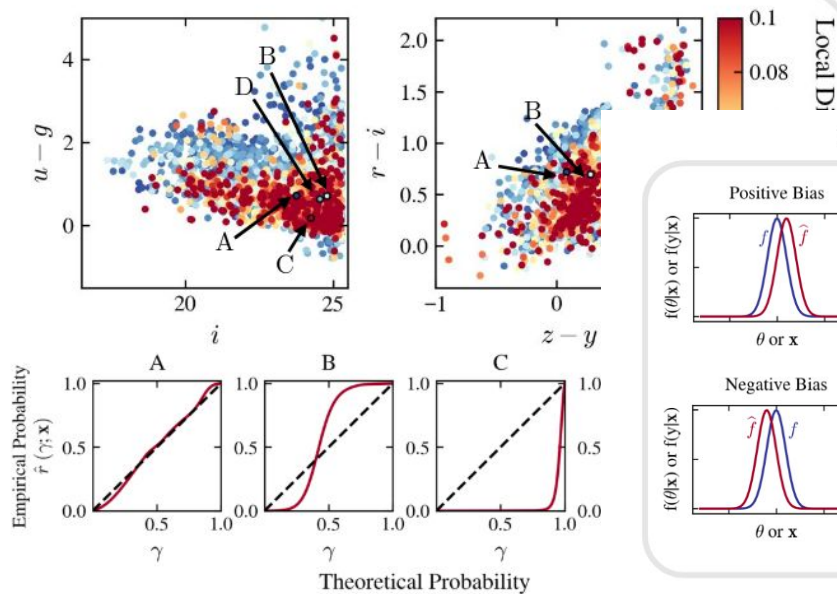
Require: initial CDE $\hat{f}(y|\mathbf{x})$ evaluated at $y \in G$; calibration set $\mathcal{D} = \{(\mathbf{X}_1, Y_1), \dots, (\mathbf{X}_n, Y_n)\}$; oversampling factor K ; evaluation points $\mathcal{V} \subset \mathcal{X}$; nominal miscoverage level α , flag HPD (true if computing HPD sets)

Ensure: new distribution $\tilde{F}(y|\mathbf{x})$, Cal-PIT interval $C(\mathbf{x})$, new density estimate $\tilde{f}(y|\mathbf{x})$, for all $\mathbf{x} \in \mathcal{V}$

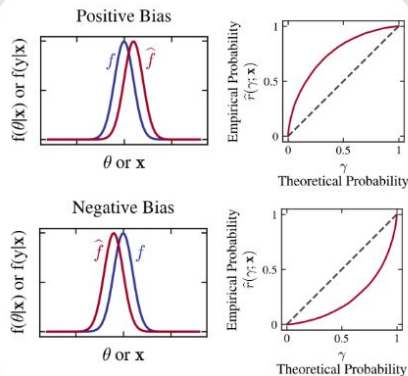
```
1: // Learn PIT-CDF from augmented and upsampled calibration data  $\mathcal{D}'$ 
2: Set  $\mathcal{D}' \leftarrow \emptyset$ 
3: for  $i$  in  $\{1, \dots, n\}$  do
4:   for  $j$  in  $\{1, \dots, K\}$  do
5:     Draw  $\gamma_{i,j} \sim U(0, 1)$ 
6:     Compute  $W_{i,j} \leftarrow \mathbb{I}(\text{PIT}(Y_i; \mathbf{X}_i) \leq \gamma_{i,j})$ 
7:     Let  $\mathcal{D}' \leftarrow \mathcal{D}' \cup \{(\mathbf{X}_i, \gamma_{i,j}, W_{i,j})\}$ 
8:   end for
9: end for
10: Use  $\mathcal{D}'$  to learn  $\hat{r}(\gamma; \mathbf{x}) := \hat{\mathbb{P}}(\text{PIT}(Y; \mathbf{x}) \leq \gamma \mid \mathbf{x})$  via a regression of  $W$  on  $\mathbf{X}$  and  $\gamma$ ,
    which is monotonic w.r.t.  $\gamma$ .
11:
12: // Map initial CDE into a new CDE by applying learnt PIT-CDF
13: for  $\mathbf{x} \in \mathcal{V}$  do
14:   // Construct recalibrated CDE
15:   Compute  $\hat{F}(y|\mathbf{x}) \leftarrow \text{cumsum}(\hat{f}(y|\mathbf{x}))$  for  $y \in G$ 
16:   Let  $\tilde{F}(y|\mathbf{x}) \leftarrow \hat{r}(\hat{F}(y|\mathbf{x}); \mathbf{x})$  for  $y \in G$ 
17:   Apply interpolating (or smoothing) splines to obtain  $\tilde{F}(\cdot|\mathbf{x})$  and  $\tilde{F}^{-1}(\cdot|\mathbf{x})$ 
18:   Differentiate  $\tilde{F}(y|\mathbf{x})$  to obtain new distribution  $\tilde{f}(y|\mathbf{x})$  for  $y \in G$ 
19:   Renormalize  $\tilde{f}(y|\mathbf{x})$  according to Izbicki & Lee (2016, Section 2.2)
20:
21:   // Construct Cal-PIT interval with conditional coverage  $1 - \alpha$ 
22:   Compute  $C(\mathbf{x}) \leftarrow [\tilde{F}^{-1}(0.5\alpha|\mathbf{x}); \tilde{F}^{-1}(1 - 0.5\alpha|\mathbf{x})]$ .
23:   if HPD then
24:     Obtain HPD sets  $C(\mathbf{x}) = \{y : \tilde{f}(y|\mathbf{x}) \geq \tilde{t}_{\mathbf{x},\alpha}\}$ , where  $\tilde{t}_{\mathbf{x},\alpha}$  is such that
       
$$\int_{y \in C_\alpha(\mathbf{x})} \tilde{f}(y|\mathbf{x}) dy = 1 - \alpha$$

25:   end if
26: end for
27: return  $\tilde{F}(y|\mathbf{x})$ ,  $C(\mathbf{x})$ ,  $\tilde{f}(y|\mathbf{x})$ , for all  $\mathbf{x} \in \mathcal{V}$ 
```

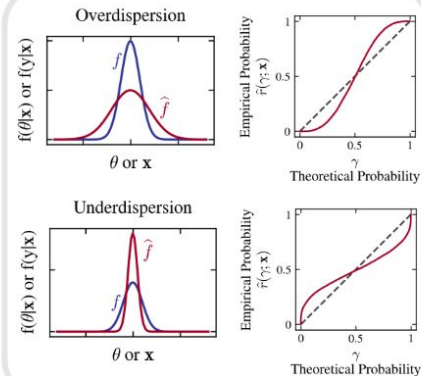
I: Local Amortized Diagnostics



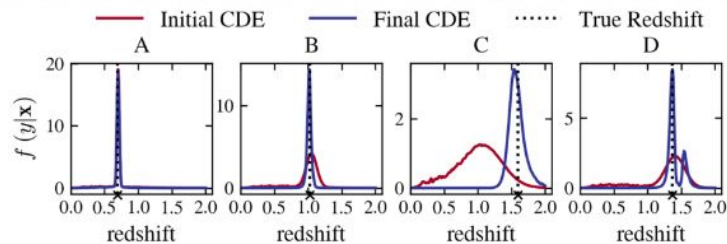
BIAS



DISPERSION



II: Reshaping of Densities



https://lee-group-cmu.github.io/cal-pit-paper/fig_1_interactive/



Photo- z Algorithm	CDE Loss
ANNz2 (Sadeh et al., 2016)	−6.88
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SkyNet (Graff et al., 2014)	−7.89
TPZ (Carrasco Kind & Brunner, 2013)	−9.55
trainZ (Schmidt et al., 2020)	−0.83
Cal-PIT	− 10.80



Mantis Shrimp: Exploring Photometric Band Utilization in Computer Vision Networks for Photometric Redshift Estimation

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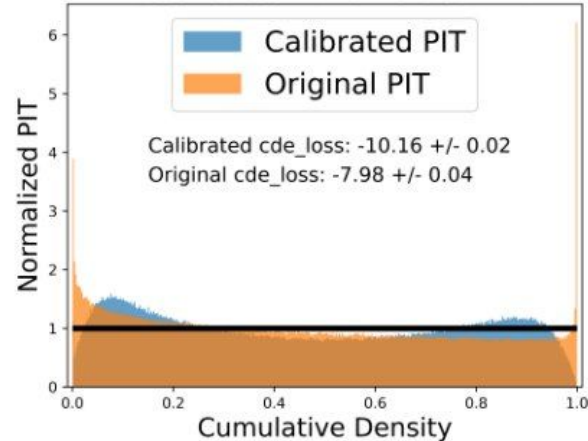
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⁷*Illinois Center for Advanced Studies of the*

⁸*Research Computing, Pacific Northwest*

Effect of CalPIT on Global PIT



Part 2

Electronic Journal of Statistics

Vol. 18 (2024) 5045–5090

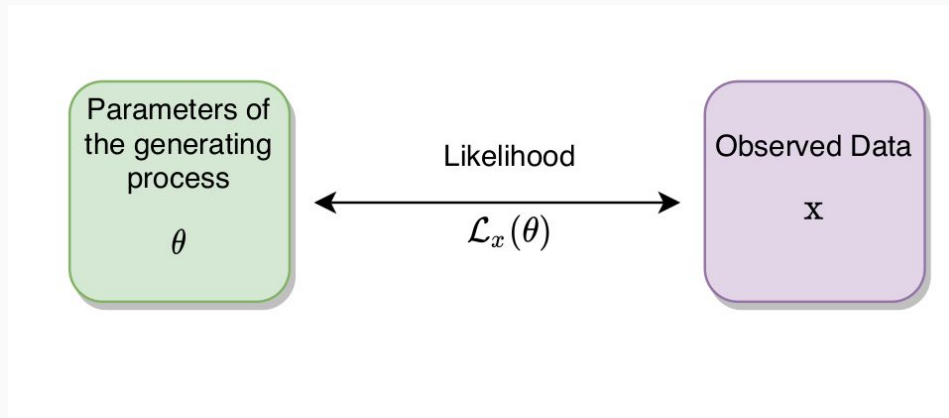
ISSN: 1935-7524

<https://doi.org/10.1214/24-EJS2307>

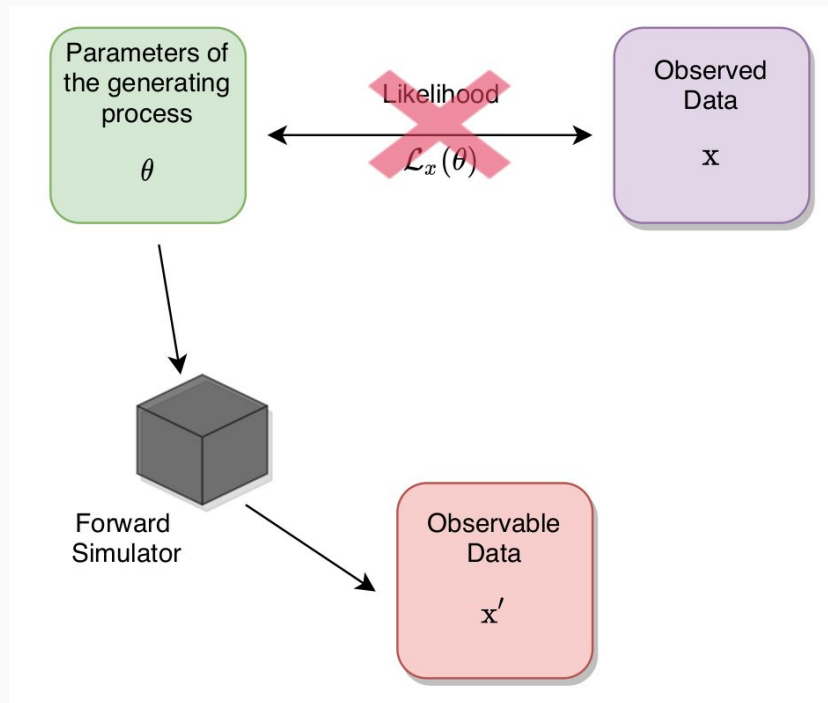
Likelihood-free frequentist inference: bridging classical statistics and machine learning for reliable simulator-based inference*

Niccolò Dalmaso^{†,1}, Luca Masserano^{†,2},
David Zhao², Rafael Izbicki³, Ann B. Lee²

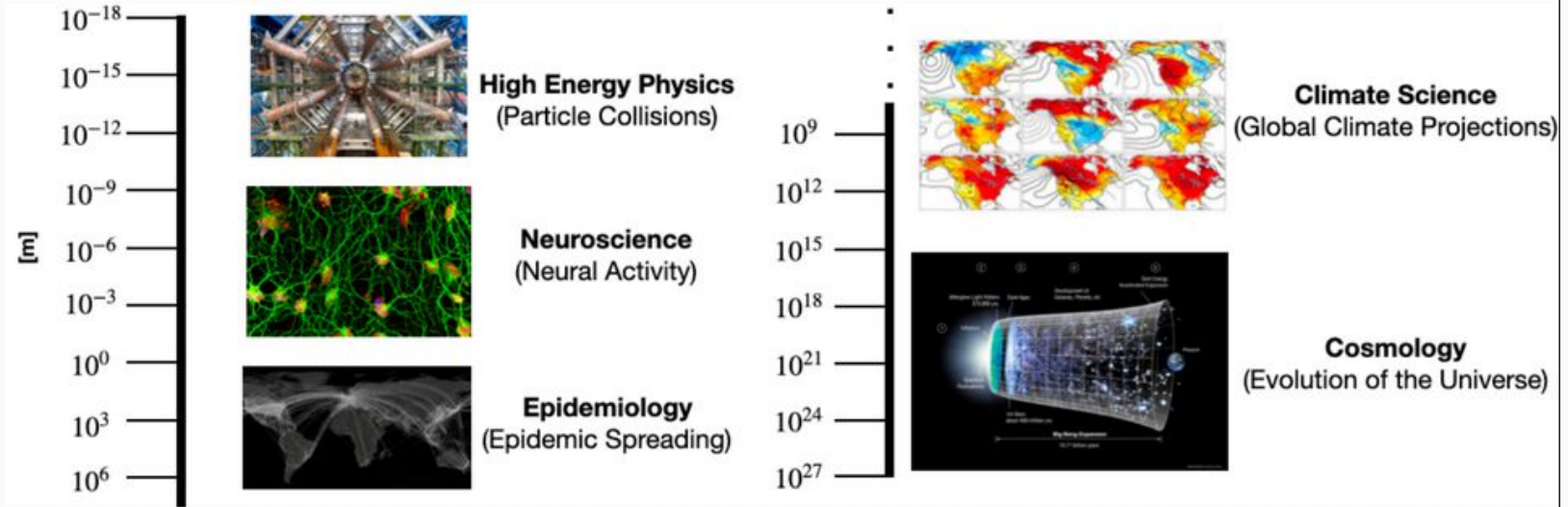
Statistical Inference



Statistical Inference



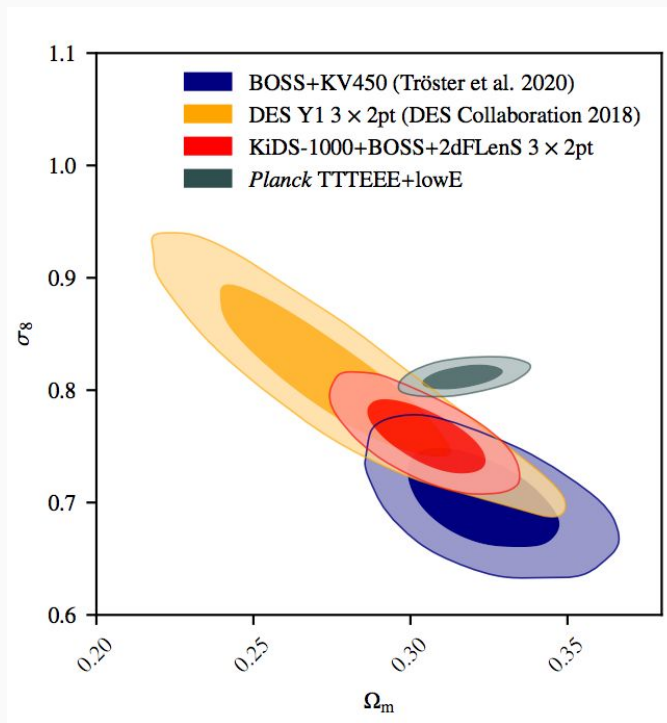
Model/theory comes in the form of simulations



Credit: Dalmasso (adapted from Cranmer et al, 2020)

How about valid frequentist inference?

$$\mathbb{P}_{\mathcal{D}|\theta}(\theta \in R(\mathcal{D})) = 1 - \alpha, \quad \forall \theta \in \Theta$$

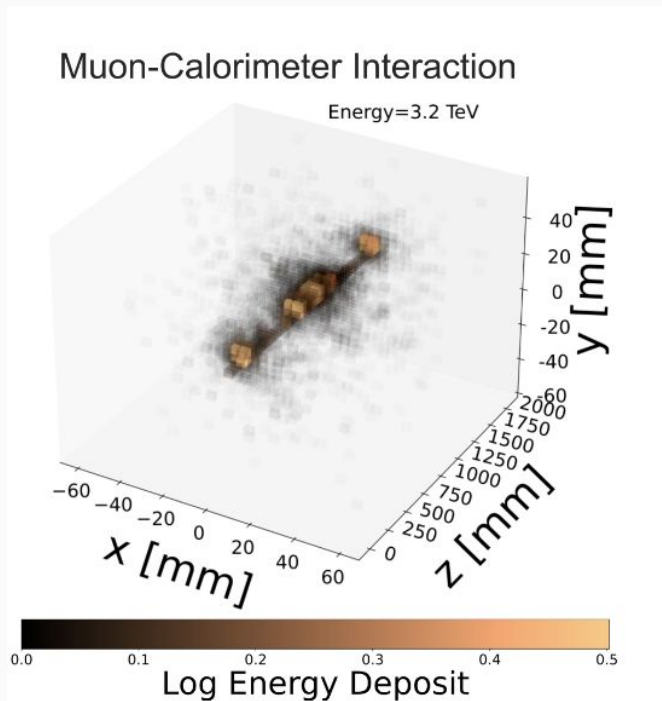


Source: KiDS collaboration 2020



$$R(\mathbf{X}) := \{\theta \in \Theta \mid \tau(\mathbf{X}; \theta) \geq C_\theta\}$$

Confidence Sets for Muon Energies using CNN



Calorimetric Measurement of Multi-TeV Muons via Deep Regression

Jan Kieseler^{a1}, Giles C. Strong^{b23}, Filippo Chiandotto^{c2}, Tommaso Dorigo^{d3}, Lukas Layer^{a43}

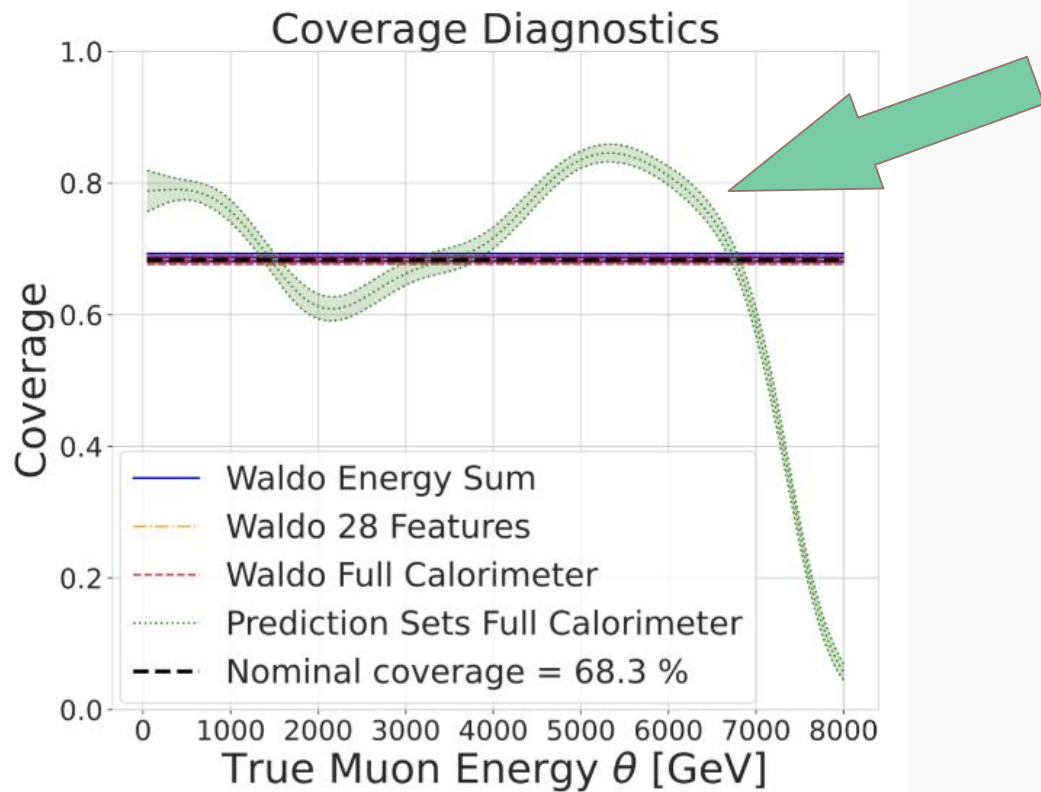
¹CERN

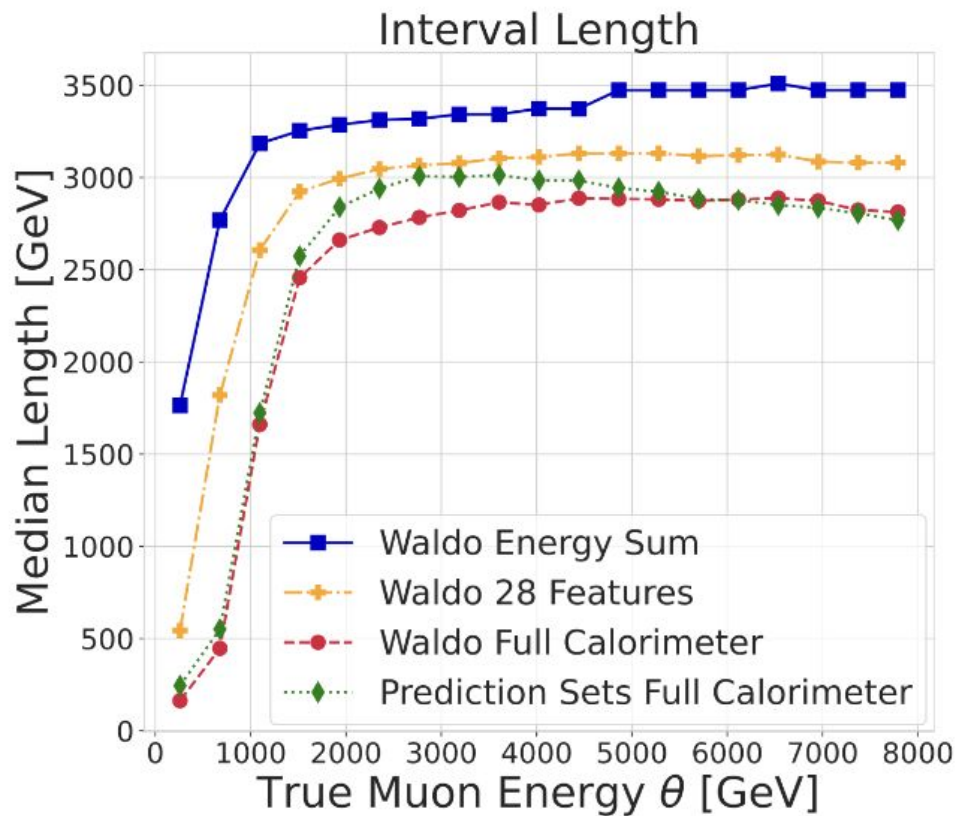
²Università di Padova

³INFN, Sezione di Padova

⁴Università di Napoli "Federico II"

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Eur. Phys. J. C (2022) 82:79 <https://doi.org/10.1140/epjc/s10052-022-09993-5>







Statistics > Methodology

[Submitted on 28 Nov 2024]

Distribution-Free Calibration of Statistical Confidence Sets

Luben M. C. Cabezas, Guilherme P. Soares, Thiago R. Ramos, Rafael B. Stern, Rafael Izbicki

Constructing valid confidence sets is a crucial task in statistical inference, yet traditional methods often face challenges when dealing with complex models or limited observed sample sizes. These challenges are frequently encountered in modern applications, such as Likelihood-Free Inference (LFI). In these settings, confidence sets may fail to maintain a confidence level close to the nominal value. In this paper, we introduce two novel methods, TRUST and TRUST++, for calibrating confidence sets to achieve distribution-free conditional coverage. These methods rely entirely on simulated data from the statistical model to perform calibration. Leveraging insights from conformal prediction techniques adapted to the statistical inference context, our methods ensure both finite-sample local coverage and asymptotic conditional coverage as the number of simulations increases, even if n is small. They effectively handle nuisance parameters and provide computationally efficient uncertainty quantification for the estimated confidence sets. This allows users to assess whether additional simulations are necessary for robust inference. Through theoretical analysis and experiments on models with both tractable and intractable likelihoods, we demonstrate that our methods outperform existing approaches, particularly in small-sample regimes. This work bridges the gap between conformal prediction and statistical inference, offering practical tools for constructing valid confidence sets in complex models.

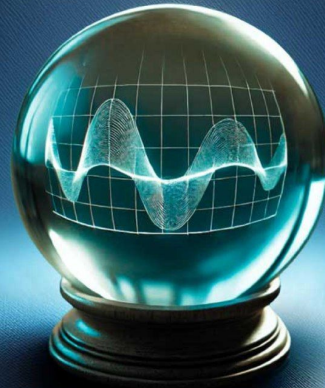


Summary

- **LADaR and Cal-PIT:** goodness-of-fit and recalibration of photo-z's to improve local calibration
- **LF2I:** confidence sets with the correct coverage for Simulation-Based Inference Problems



**Machine Learning
Beyond Point Predictions:
Uncertainty Quantification**



Rafael Izbicki

<https://rafaelizbicki.com/UQ4MLpt>

Thanks!

Questions?

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<https://rafaelizbicki.com/>



Small

Statistical Machine Learning Lab

Alternative resources

Here's an assortment of alternative resources whose style fits the one of this template:

- Flat sparkling stars collection
- Vector dividers collection in hand drawn style
- Vector calligraphic ornamental divider collection

